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**Kernels for  
Vector-Valued  
Functions: A Review**

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# Kernels for Vector-Valued Functions: A Review

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## Kernels for Vector-Valued Functions: A Review

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### Abstract

Kernel methods are among the most popular techniques in machine learning. From a regularization perspective they play a central role in regularization theory as they provide a natural choice for the hypotheses space and the regularization functional through the notion of reproducing kernel Hilbert spaces. From a probabilistic perspective they are the key in the context of Gaussian processes, where the kernel function is known as the covariance function. Traditionally, kernel methods have been used in supervised learning problems with scalar outputs and indeed there has been a considerable amount of work devoted to designing and learning kernels. More recently there

has been an increasing interest in methods that deal with multiple outputs, motivated partially by frameworks like multitask learning. In this monograph, we review different methods to design or learn valid kernel functions for multiple outputs, paying particular attention to the connection between probabilistic and functional methods.

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## Introduction

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Many modern applications of machine learning require solving several decision making or prediction problems and exploiting dependencies between the problems is often the key to obtain better results and coping with a lack of data (to solve a problem we can *borrow strength* from a distinct but related problem).

In *sensor networks*, for example, missing signals from certain sensors may be predicted by exploiting their correlation with observed signals acquired from other sensors [72]. In *geostatistics*, predicting the concentration of heavy pollutant metals, which are expensive to measure, can be done using inexpensive and oversampled variables as a proxy [37]. In *computer graphics*, a common theme is the animation and simulation of physically plausible humanoid motion. Given a set of poses that delineate a particular movement (for example, walking), we are faced with the task of completing a sequence by filling in the missing frames with natural-looking poses. Human movement exhibits a high degree of correlation. Consider, for example, the way we walk. When moving the right leg forward, we unconsciously prepare the left leg, which is currently touching the ground, to start moving as soon as the right leg reaches the floor. At the same time, our hands move synchronously with

## 2 Introduction

our legs. We can exploit these implicit correlations for predicting new poses and for generating new natural-looking walking sequences [106]. In *text categorization*, one document can be assigned to multiple topics or have multiple labels [50]. In all the examples above, the simplest approach ignores the potential correlation among the different output components of the problem and employ models that make predictions individually for each output. However, these examples suggest a different approach through a joint prediction exploiting the interaction between the different components to improve on individual predictions. Within the machine learning community this type of modeling is often broadly referred to as *multitask learning*. Again the key idea is that information shared between different tasks can lead to improved performance in comparison to learning the same tasks individually. These ideas are related to *transfer learning* [12, 20, 74, 97], a term which refers to systems that learn by transferring knowledge between different domains, for example: “what can we learn about running through seeing walking?”

More formally, the classical supervised learning problem requires estimating the output for any given input  $\mathbf{x}_*$ ; an estimator  $f_*(\mathbf{x}_*)$  is built on the basis of a training set consisting of  $N$  input–output pairs  $S = (\mathbf{X}, \mathbf{Y}) = (\mathbf{x}_1, y_1), \dots, (\mathbf{x}_N, y_N)$ . The input space  $\mathcal{X}$  is usually a space of vectors, while the output space is a space of *scalars*. In multiple output learning (MOL) the output space is a space of *vectors*; the estimator is now a *vector-valued function*  $\mathbf{f}$ . Indeed, this situation can also be described as the problem of solving  $D$  distinct classical supervised problems, where each problem is described by one of the components  $f_1, \dots, f_D$  of  $\mathbf{f}$ . As mentioned before, the key idea is to work under the assumption that the problems are in some way related. The idea is then to exploit the relation among the problems to improve upon solving each problem separately.

The goal of this survey is twofold. First, we aim at discussing recent results in multi-output/multitask learning based on kernel methods and Gaussian processes providing an account of the state of the art in the field. Second, we analyze systematically the connections between Bayesian and regularization (frequentist) approaches. Indeed, related techniques have been proposed from different perspectives and drawing

clearer connections can boost advances in the field, while fostering collaborations between different communities.

The plan of the monograph follows. In Section 2 we give a brief review of the main ideas underlying kernel methods for scalar learning, introducing the concepts of regularization in reproducing kernel Hilbert spaces and Gaussian processes. In Section 3 we describe how similar concepts extend to the context of vector-valued functions and discuss different settings that can be considered. In Sections 4 and 5 we discuss approaches to constructing multiple output kernels, drawing connections between the Bayesian and regularization frameworks. The parameter estimation problem and the computational complexity problem are both described in Section 6. In Section 7 we discuss some potential applications that can be seen as multi-output learning. Finally we conclude in Section 8 with some remarks and discussion.

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